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# Research and Development Technical Report ECOM-2836

HIGH-EFFICIENCY TRANSISTOR CW RF
POWER AMPLIFIER

by

D. R. Lohrmann

May 1967



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#### TECHNICAL REPORT ECOM- 2836

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#### HIGH-EFFICIENCY TRANSISTOR CW RF POWER AMPLIFIER

Ву

D. R. Lohrmann

DA Task No. 1E6 34301 D246 01

MAY 1967

#### COMMUNICATION? ADP LABORATORY

#### **ABSTRACT**

Research work on VHF transistor power amplifiers of the switched type demonstrates semi broadband designs yielding collector efficiencies as high as 80% at 40W output in the frequency range from 30 to 76 MHz. A laboratory model of such an amplifier was built. It was designed to fit the AN/VRC-12.

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<sup>\*</sup>Cy of Article written by Mr. D.R. Lohrmann, entitled: Amplifier has 85% Efficiency While Providing up to 10W Power over a Wide Frequency Band, March 1966 Issue of the Electronic Design Magazine.

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#### HIGH-EFFICIENCY TRANSISTOR CW 3F POWER AMPLIFIER

#### I. INTRODUCTION

Recent progress in semiconductor development made available transistors which enabled us to develop high-efficiency power transmitter circuits in the VHF range.

#### II. PURPOSE

The purpose of the work was to find ways to build RF CW transistor power amplifiers with efficiencies as high as possible. This is especially important for portable sets, where one tends to save weight of batteries and heatsinks.

#### III. DISCUSSION

#### 1. General Considerations

The approach taken is a semi-broadband mode, in which the transistor is used as a switch. Therefore, the principle is confined to use in CW amplifiers, like in FM sets.

Collector efficiencies up to 80% at 40% output at 10 db gain have been observed, see fig. 1 and fig. 2.

The transistor used was #5067 by TRW Semiconductors Inc. (TRWS). thad been developed under contract DA 28-043-AMC-02162(E).

The main problem out of the many that had to be solved, was parametric oscillations on half signal-frequency or lower. They are caused by the nonlinear collector to base and base to emitter capacities, which are swept from maximum to minimum and back at each cycle of the signal. One way the effect can easily be eliminated is to insert attenuating resistors between collector and emitter of the transistor, however, this results in reduced efficiency and hence other ways were sought and found to overcome the problem. Unfortunately, there is no reasonably useful theory on the instability of circuits containing nonlinear reactances at present, nowever, we succeeded in making progress towards a preliminary solution to the problem.

#### 2. Advantages found in using this amplifier in VRC-12

#### 2.1 Reduction of battery power

The battery power drawn was reduced from 47W down to 17.8W in receive and from 225W down to 110W in the transmit mode. This reduction is particularly valuable if the set is to be used as a relay station. The reason why the power in receive is cut down so much also

is that the current set uses two indirectly heated tubes in the power amplifier of the transmitter, which have to be kept heated in standby during receive in order to be ready instantaneously for transmit.

## 2.2 Increased reliability

No tubes would have to be changed any more in the power amplifier. In the old VRC-12, one trouble spot had been the high voltage supply. This would be eliminated, adding greatly to the reliability of the set.

- 2.3 Continuous transmit duty possible, even at 670C
- 2.4 The fan noise has been eliminated with use under normal environment conditions

## 2.5 Modernizing present sets

VRC-12 sets currently being used could be modernized into models with transistorized transmitter power amplifiers by exchanging subassemblies. This could even be done in the field. The only tool required would be a screwdriver. If the transmit PA module of VRC-12 should be transistorized the procedure in changing would be as follows:

- a. Take cut old transmit FA module and screw in new one.
- b. Take out old power say My module and screw in new one.
- c. Take out relay K406 and screw in dummy.
- d. The low pass filter in the antenna line is removed.
- e. Screw in additional isolation amplifier, containing a transistor 20918 and some components. (Schematic of isolation amplifier, see figure 4.)

The reason for the latter is that the injection of the transmit RF into the FA module carries a spurious oscillator signal, which is 11.5 MHz off the signal frequency. Formerly, the PA contained additional tuned circuits, which eliminated this spur. However, in our breadband approach we therefore had to solve the problem in a different way by inserting a broadband isolation amplifier stage between transmit driver and HF tuner in the VRC-12. (Schematic of amplifier stage, see figure ).) See also changes in overall circuits, figure 6.

The necessary connections can be made easily without using a solder gun.

## 3. Description of the amplificr

#### 3.1 General

The amplifler amplifies 100 W of rf input power up to 32W output power 4 ldb.

The frequency range from 30 to 76 MHz is covered in three bands, from 30 to 40, 40 to 53 and 53 to 76 MHz. There are no tuning elements like tuning capacitors or tuning coils in the setup. The nominal battery voltage used is 25.5V.

## 3.2 The predriver stage, see fig. 5

It is equipped with transistor 203666 by RCA. Switch S<sub>1</sub> reduces the input power in the two lower bands, since the final power amplifier stage needs 4W of drive power only in the highest band, and less in the lower ones.

In the collector line there is a broadband transformer. It matches the collector of the 2N3866 to the input impedance of the following stage which is approximately  $\theta\Omega$ . This next stage requires about 1W of input power.

For a 17V peak voltage swing on the collector and for 1W of output power, the transformer has to transform the load impedance of  $8\,\Omega$  up to  $150\,\Omega$  .

The transformer was built with a Q 3 Ferrite Cup Core. There were five turns of #18 magnet wire on the primary and one turn of copper foil on the secondary. The copper roil was 1/4" wide; it was wrapped directly on the cylindrical primary coil. The coupling factor achieved that way was .85.

The resistor of 1.5% ohms in parallel to the collector of the 2N3666, as well as the 5 and 10  $\Omega$  resistors at the input of the next stage, was necessary to prevent parametric oscillations appearing on 1/2 signal frequency and lower.

## 3.3 The driver stage

The driver stage uses a transistor 2N3632 by RCA. It delivers between 3 and 4.5W driving power to the power stage. The transistor is self-biased.

First, we had tried to design this stage broadbanded also using 2N3375. However, we could not safely eliminate oscillations on subharmonics, which occurred on several points in the frequency range. The amplifier worked very well into a broadband  $50\Omega$  real load, however,

when it was connected to the final stage these oscillations appeared. At a given frequency the effect could be made to disappear if the cable length between driver and final stage was varied. It seems possible that the nonlinear reactance in the base emitter circuit of the PA stage was involved in addition.

Since the theory indicated that this effect of subharmonics can be eliminated by showing a very low impedance on one half the signal frequency or lower frequencies to the pumped collector or base capacity respectively, we used a bandfilter for each of the three output ranges in the collector circuit of the driver.

The filters were designed as one section way types, the input parallel coil of the filter serving as a feeding line for the DC to the collector. Thereby the coupling capacitor could be eliminated also.

## 3.4 The power amplifier stage

The power amplifier is equipped with a transistor 5067 by TRWS. As mentioned, this transistor was developed by TRWS, with a design goal of  $B_{\rm VCES} = 100V$ , 50W output power at 76 MHz with 80% collector efficiency at 10 db gain.

## 3.4.1 The input matching circuit

matches the 50 \( \Omega\) impedance of a driving source to the approximately .9 \( \Omega\) input impedance of the transistor 5067. The input impedance of the base lead of the 5067, at a distance 1/8" from the case was measured under operational conditions. This was done by measuring voltage at the base lead, the current going to the base, and the phase angle between them. For achieving this, a Tektronix sampling scope was used, which was synchronized externally. From a signal source, capable of delivering a maximum of 40% the current was impressed to the base thru a 50 nH coil. From measurements of absolute value and phase angle of the voltage at the input side of the coil and at the base side of the coil the input impedance was calculated. One has to see to it that the ground connection of the probe at the base is very short, and very close to the point of measurement at the base. Since the wave form is distorted, low pass filters were used before entering the scope.

The results are plotted in figure 7. The Smith chart is referenced to 11. One can see that the input impedance is in the order of 11, and in the frequency range between 30 and 76 MHz it behaves approximately like . A real in series with a 4000 pF capacitor and a 3.2 nH inductivity.

The transformer uses a 20K 12 ferrite cup core, airgapped to result in 20nH/turn square. The primary of this transformer consists of 3 turns of mylar coated copper foil, the foil being lmm wide. On top of these three turns, which were supported by a bobbin, one turn of copper tape, 5 mm wide was wrapped around. This way, a stray factor of 20% can be achieved, or, in other words a coupling factor of .9 is obtained.

The transformer transforms down to about 3 ohms; the broadband transforming network which follows transforms these 3 ohms down to .9 ohm.

For a summary on transformers see appendix of this report. Figure 8 shows the input matching circuit for the #5067 used, and its equivalent circuit. Mechanically, it is very simple and inexpensive. Functionwise electrically, it is not quite so simple. Parallel and stray inductance of the transformer are combined into parts of a general broadband transformation circuit, see figure 9, [1].

the network transforms and has a bandpass characteristic, having  $f_u$ ,  $f_1$ , and  $f_m$ , as upper, lower and center frequencies.

For an impedance transformation of  $R_1/R_2 = n = 4$ , we read from figure 9:

$$\frac{\mathbf{f_u} - \mathbf{f_1}}{\mathbf{f_m}} = .6$$

resulting in about 20% mismatch at the frequency limits. If  $f_u = 76$  MHz, and  $f_m = \sqrt{f_1 \cdot f_u}$  we get  $f_m = 56.6$  MHz, and  $f_1 = 42$  MHz.

Since our band goes down to 30 MHz, this will give us some increased mismatch on the lower frequency end. We can tolerate this however, because on the lower frequency end we need much less driving power (-3db) anyhow.

 $\rm R_2$ , which constitutes the series input resistance of the transistor, was measured to be about .9 ohm; in the actual circuit it seems to be closer to 1.2 ohms. From [4], figure 8 and figure 9 we see that

$$X_1 = 2 \pi f_m I_1 = R_2$$
  $= 1.2 \Omega$ 

In the actual circuit, this inductivity is in the base lead of the transistor. Therefore it does not appear in the circuit diagram. The series capacity of 4000pF in the equivalent circuit of the transistor input impedance is neglected. Then we get the other values to be

$$X_2 = 1/2 \, \text{T} \, f_m \, C_2 = R_2 \, \sqrt{\frac{n}{m-1}} = R_2 \cdot 2 = 2.4 \, \Omega$$

$$C_2 = 1170 \, \text{pF}$$

$$X_3 = 1/2 \, \text{T} \, f_m \, C_3 = R_2 \, \sqrt{n(\sqrt{n}-1)}$$

$$C_3 = 1170 \, \text{pF}$$

$$X_4 = R_2 \, \frac{n}{\sqrt{n-1}} = 2 \, \text{T} \, f_m \, \cdot L_4$$

$$L_h = 14 \, \text{nH} \, \cdot \cdot$$

The 1100pF capacitors were made out of a 2200pF ceramics capacitor by Mucom, which contains two 1100pF capacitors sandwiched together and paralleled. The wire paralleling the top electrodes of the two chips was cut, this way rendering the two 1100pF capacitors in series. Then the coating of the capacitor was removed on one side, and subsequently soldered with this surface to the ground plain.

## 3.4.2 Output Circuit

The output circuit is designed as described in [2] see appendix. The DC current is supplied to the collector via three chokes, one for each band. Care must be taken to insure that the collector at no frequency within the band sees a short circuit on the second harmonic. Otherwise at that frequency the power output and the efficiency will be greatly diminished. The same is valid for the base circuit. Seen from the base into the matching circuit there should not be a short circuit on the second harmonic.

For load impedance measured at the collector see figure 11. The outure power specified is  $P_{\text{Out}}=40W$ , the battery voltage is  $V_{\text{B}}=24.4V$ , and the saturation voltage is assumed to be  $V_{\text{CESat}}=3V$ .

Then from [2] we have  $R_{\bullet} = .85 (V_B - V_{CESat})^2 \approx 10 \Omega$ .

Pout

This is the impedance the collector has to see on the fundamental. Therefore, the transformer behind the collector - low pass filter section has to transform from  $10\Omega$  up to  $50\Omega$ . An example for calculating the low pass filter section following the collector is given for band 3, 53....76 MHz, see [2].

$$Z_{\overline{q}}$$
 = 1.1 R<sub>o</sub> = 11  $\Omega$   
 $f_{g}$  = 1.5  $f_{u}$  . With  $f_{u}$  = 76 MHz,  
 $f_{g}$  = 114 MHz  
 $C = \frac{1}{2 T f_{g} Z_{v}} = \frac{1}{2 T \cdot 114 \cdot 10^{6} \cdot 11} = \frac{127 \text{ pF}}{2 T \cdot 114 \cdot 10^{6} \cdot 11}$ 

The dynamic collector capacity of the transistor #5067 is about 110 pF. Therefore, only a small trimmer is required on the collector side of the T - filter section.

$$L = Z_{\overline{Y}}$$
 =  $\frac{11\Omega}{\overline{Y} \cdot f_g}$  = 30 nH = 30 nH

is the inductivity of this low pass filter section.

The capacitor on the output side of the filter was replaced by a series circuit, which provides a short circuit on double, mid band frequency, however exhibits a capacitive impedance of an equivalent of 127 pF at the mid band frequency. This has been found to improve the efficiency.

The transformer is coupled to this low pass section by a capacitor, which is designed to compensate the stray inductivity of this transformer in the center of the band.

The transformers in all three bands are cup cores of ferrite 20K 12, 14 millimeter diameter, airgapped to  $20nH/turn^2$ . In the lowest band there are 6 turns of #22 wire, bifilar wound and tapped at 3 turns; in the center band 4 turns with tap at 2, and 5 turns with tap at 2 of #20 wire for the highest band.

These transformers are followed by low pass filters, which provide a total harmonic suppression of better than 75 db, see figure 10. The filters have a pass band attenuation of less than .7 db.

### 3.5 Protecting circuits

Figure 5 shows the protecting circuit. Basically, it acts by reducing the DC supply voltage for driver and power amplifier stages. The three power transistors (Silicon RNP 2N3791 by Motorola) in parallel act as the regulating unit. The whole circuit performs the following functions:

- 3.5.1 <u>High current keying switch</u>. (activated by the low current keying relays K401 in the frame.) When the transmitter is keyed, it supplies DC to the power amplifier.
- 3.5.2 <u>Voltage regulator</u>. Up to 26V battery voltage the transistors 2N3791 are switched in completely. Above that voltage, the output voltage is kept constant at 26.5V, see figure 12.
- 3.5.3 Transient suppressor. Any transient voltage spikes coming from the DC supply (up to 80V) are suppressed by the circuit.
- 3.5.4 Current limiter. If the output is loaded with more than 3.5 A, the output voltage degrades, the current rising to approximately 4 A in the short circuit condition. This is a further measure to protect the power amplifier, see figure 13.
- 3.5.5 Mismatch Protector Between the low pass filters and the antenna terminal there is a directional coupler inserted, see figure 5. The DC output voltage of this sensor is proportional to the amount of RF power being reflected back from the antenna in case of mismatch, see figure 14. If the output voltage of the VSWR sensor exceeds a certain threshold, being set by potentiometer P2 in figure 5, it starts reducing the DC supply voltage of the driver and power amplifier stage. This way the amount of reflected RF power is kept at a constant value above a VSWR of 3.
- 3.5.6 Peak Voltage Protector If the peak voltage on the collector of the power amplifier exceeds a given value, (85V), the DC driving voltage is reduced as well. The peak detector sensor is shown in figure 5. The level at which reduction of driving DC voltage starts can be set by potentiometer P3 of figure 5.

## 3.6 Influence of mismatch of antenna

As a necessary consequence of this high collector efficiency, rf wise the amplifier somehow acts like a stiff source; its internal impedance is by necessity not matched to the load. Therefore, variations of the antenna load cause much larger variations of the power

delivered to the load than in the "matched" case. In a sense, the amplifier behaves like a power outlet on the wall. If one reduces the internal impedance of, say a solder gun by a factor of three, it will draw three times more power. Similarly, if the antenna impedance is varied along the circle of VSWR = 3, the power delivered to the load will vary approximately between a minimum of 1/3 and a maximum of three times of that rated power, which it would deliver at a load having a VSWR of one. In other words, having an output power of 40W at a real antenna load impedance of 50 ohms, the amplifier will send 13W and a maximum of 120W into the load, if we vary a minimum of this load along a VSWR = 3 circle. Of course, the 120W point is not reached in practice, since the overload protector circuits start acting long before. Otherwise, the power transistor would be destroyed. See Figure 15 for a measurement of output power delivered to the load, where the load was moved on a VSWR=3 circle. Figure 15a shows calculated values.

Here a few remarks about the equivalent circuit of the transmitter output are added. The transmitter stage as described can always be represented as a source of EMF E, a series resistor  $R_{\rm O}$  and a piece of transmission line, having characteristic impedance  $Z_{\rm O}=50\,\Omega$  and length 1, see figure 16. These parameters are vital for understanding the various mismatch conditions. They can be measured in the following way:

The amplifier is loaded with a real load R<sub>2</sub> which differs from the nominal load  $Z_0$  by a factor of 1.5...3, in our case, say with  $17\Omega$ . Between the amplifier and this load there is inserted a directional type power meter and a transmission line, having  $Z_0 = 50\Omega$  and being variable in length 1. In varying 1, the transmitter sees a load which varies along the circle VSWR = constant = 3. The power meter will measure a maximum forward going power  $P_{f \text{ max}}$  and a minimum forward going power  $P_{f \text{ min}}$ . Then, the resistor  $R_0$  in equivalent circuit figure 16 is found

Ro = Z<sub>0</sub>

$$\frac{1 - \frac{R_2}{Z_0} \sqrt{\frac{P_{f \text{ max}}}{P_{f \text{ min}}}}}{\sqrt{\frac{P_{f \text{ max}}}{P_{f \text{ min}}}} - \frac{R_2}{Z_0}}.$$

 $P_{f~max}$  and  $P_{f~min}$  we find from figure 15, however  $P_{f~max}$  must be referred to the nominal battery voltage of 25.5V that is, without the action of the DC protecting circuit.

$$P_{f min} = 21W;$$
  $P_{f max} = 63W$   $\frac{25.5V^2}{19V^2} = 113W.$ 

$$R_2$$
was 17 $\Omega$ ,  $Z_0 = 50 \Omega$ , thus with  $Z_0 = VSWR = 3$  we find

Further, 
$$R_0 = 5.5$$
.

Further,  $R_0 + R$ 

$$E=2 \frac{}{Z_0 + R}$$
 $P_{fmax} \cdot Z_0$ 

With  $R_o = 5.5\Omega$ ,  $R_2 = 17\Omega$ ,  $Z_o = 50\Omega$  and  $P_{fmex} = 113W$  we find E = 50V.

It is interesting to note that in going with the load along a VSWR = constant circle, the maximum loss in the transistor does not occur at maximum power output (see figure 15) but at a complex load with 45° capacitive phase angle.

3.6.1 Closer antenna matching tolerance required One can see from these considerations that closer tolerances of antenna matching are required, using, e.g., centerfed whips and better matching networks, in order to get the whole benefit of the design possibility. The benefits are that power consumption is less, hence smaller batteries can be used, heatsinks become smaller, and blowers for cooling can be avoided.

#### 4. Miscellaneous

4.1 The fan. The power dissipated in the set itself has been cut from 200W down to 70W. Therefore, the fan need not be switched on during transmit keying. However, it has been left in the set in order to meet marginal environmental conditions, like 65°C ambient temperature, or if the set is heated up by direct sun radiation. In this laboratory model, the switch for the fan is operated by a thermal switch located on the heat sink. This is set to turn on the fan if the temperature on the heat sink exceeds 78°C.

Currently, the fan motor has been driven by a 400 Hz two phase voltage, being supplied by a converter in the power supply. This converter, which contains two heavy coils and a transformer, can be replaced by a transformerless induction motor, being supplied by Rotating Components Inc., Bayshore, N.Y. (RCI No. 15SD-1A). Preliminary tests indicate that this fan works well. At 25.5V battery voltage it draws .48A of DC current. At 22V battery voltage there is still ample starting torque. The fan has not been built into the feasibility model, since its diameter is slightly greater than that of the old fan (36 mm diam).

It would have been too costly as far as time is concerned to change the mechanics of our feasibility model to fit this fan in; however, if additional models of the amplifiers should be

built, it is recommended to use this transformerless induction motor fan. Probably, however, the 1:00 Hz source could not be eliminated entirely, since it is used for driving servo motors in the push-button type VRC-12. Otherwise, we would get two different types of power supplies, which might be bad for logistics.

## 4.2 The power supply module

The power supply module has been stripped of its high voltage converter, see figure 17. The choke L9001 could be reduced to a 1"-diameter ferrite cup core, since the DC current to be handled is only 1/2 of what it was before.

- 4.3 Remarks on mechanical design. The amplifier in its present form represents a feasibility study. Therefore, a number of mechanical changes would be necessary before entering fabrication. Changes recommended:
- nished as follows: 30...53 and 53...76 MHz by ordinary mechanical band-switch contained in present VRC-12. The additional switch position for 30...40 MHz is achieved by Ledex, acting as a motor. The information is derived by a cam which is positioned on the shaft that formerly drove the tuning capacitor and the variometer. The cam activates a microswitch, which switches the Ledex. The Ledex seems to be reasonably good, on a life test we obtained in excess of 500,000 operations till failure. After about 650,000 operations the main shaft froze. At that time, the contacts were worn down also. In case a high reliability design would be desired, some changes in the Ledex might be required. Also, the current should be switched by a high reliability transistor, so sparking on the contacts could be eliminated. Eventually, the design should be changed such that all three positions are served by the Ledex, the Ledex having three positions.
- 2. Along with this, a regrouping of mechanical parts should take place. The three regulator power transistors should go on a common heat sink, mechanically assembled together with the regulator printed circuit board. The power amplifier and the driver amplifier would be built onto a single printed board, eventually replacing the rotary switch on the driver assembly by four miniature shift switches, being located where needed electrically.

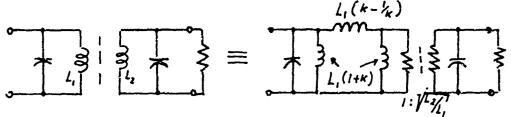
The three output filters and the VSWR detector and switch circuit should be unified in a single block.

## 5. Appendix A

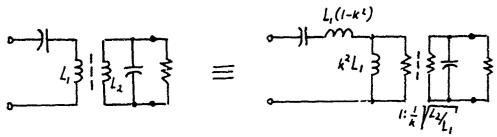
## 5.1 Some remarks about transformers

To improve matching and to extend bandwidth the following methods can be taken.

5.1.1 The transformer, if taken as an inductive 77 - network, receives a proper parallel capacitor at the input and output. Thus, the configuration of a wideband - bandfilter is obtained. This way, given the stray factor or coupling coefficient of the transformer, its 77 - ersatz circuit is calculated, and then the capacities are designed according to well-known broadband-bandfilter design.

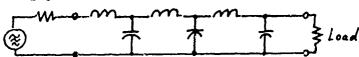


5.1.2 The transformer, if taken as an inductive type L ersatz network, can be complemented into a half-bandpass-filter Tsection.



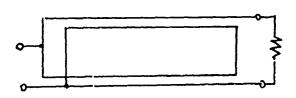
The same thing can be done complementing it to  $\alpha$  half  $\mathbb{T}\text{-section.}$  The design goes along well-known principles of bandpass filter design.

5.1.3 Transformation by use of "tapered" low pass filter design, see [3]



An analogue of this is the exponential line transformer in transmission line technique.

5 1.4 Guanella type transmission line transformer, see [4], [5], for very broadbanded applications.



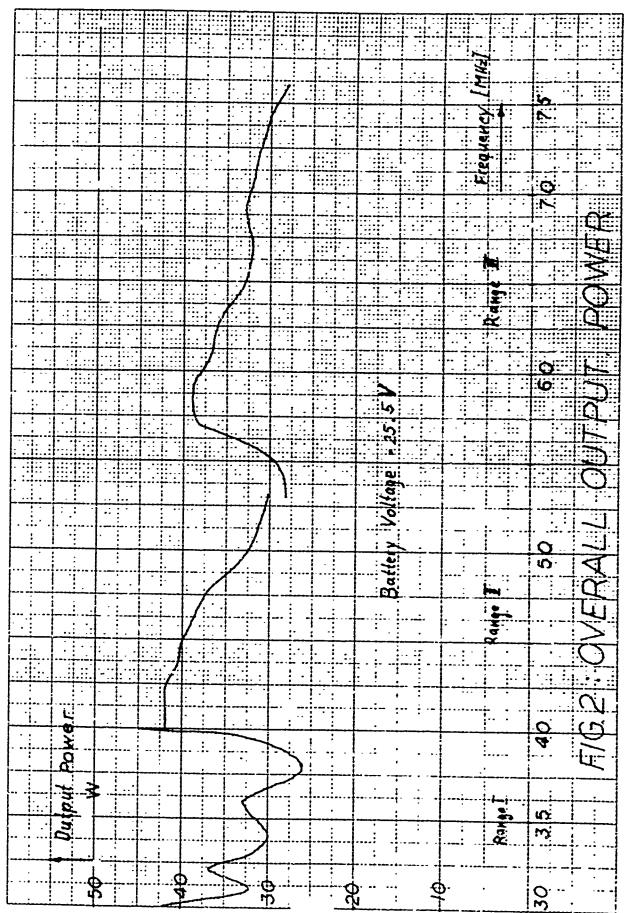
## LITERATURE INDEX

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- D.R. Lohrmann, Amplifier has 85% Efficiency While Providing Up to 10W Power Over A Wide Frequency Band, Electronic Design, March 1966, page 38. (See App. B, pp 35-40 of this technical report.)
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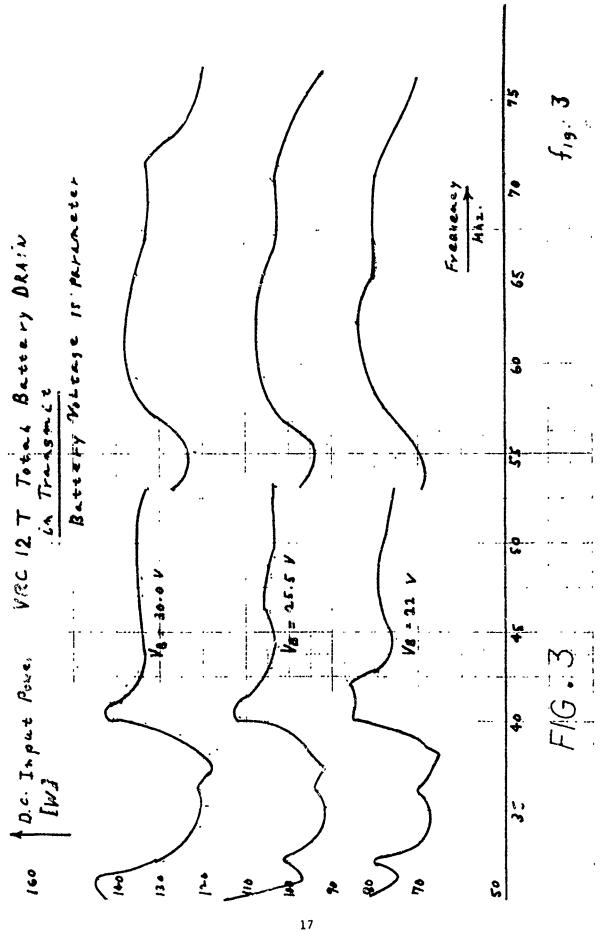
#### ACKNOWLEDGEMENT

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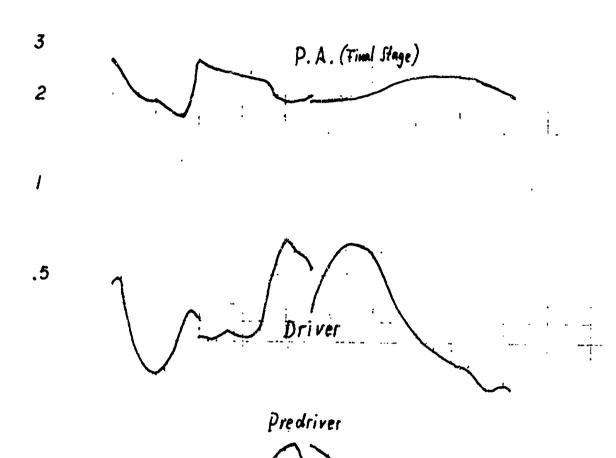


FIG. 3A:

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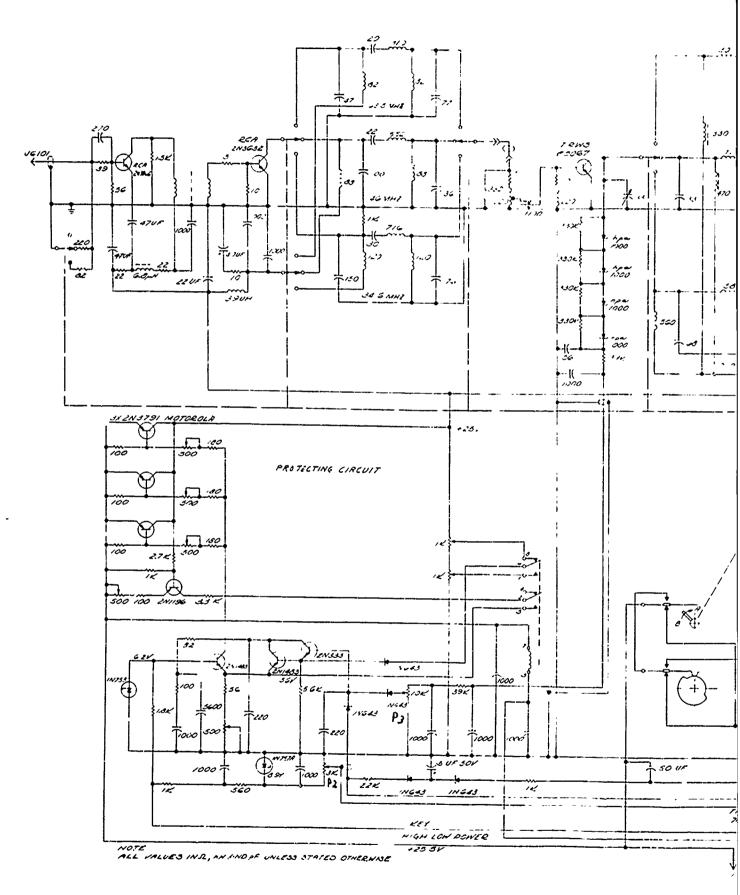
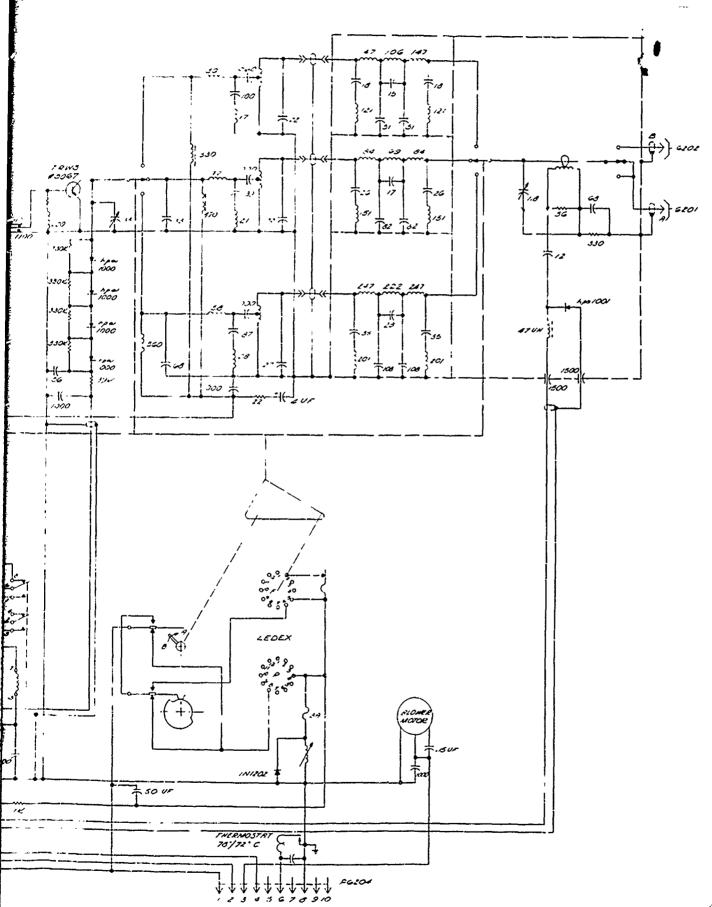


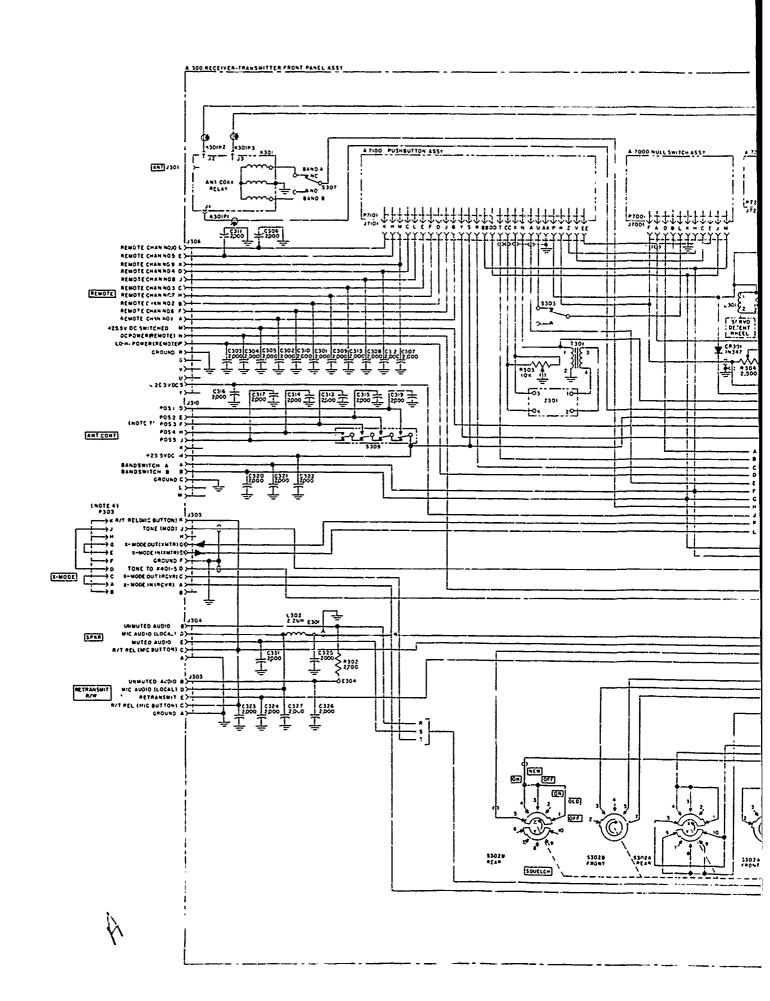
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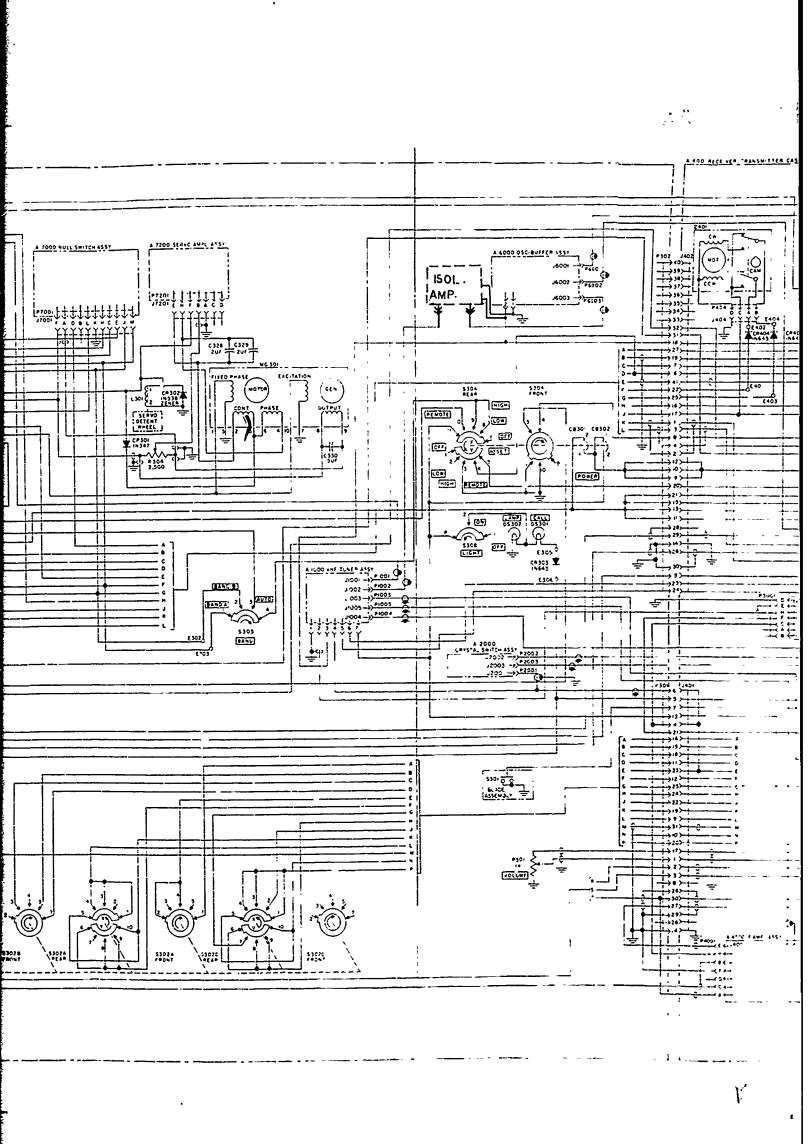


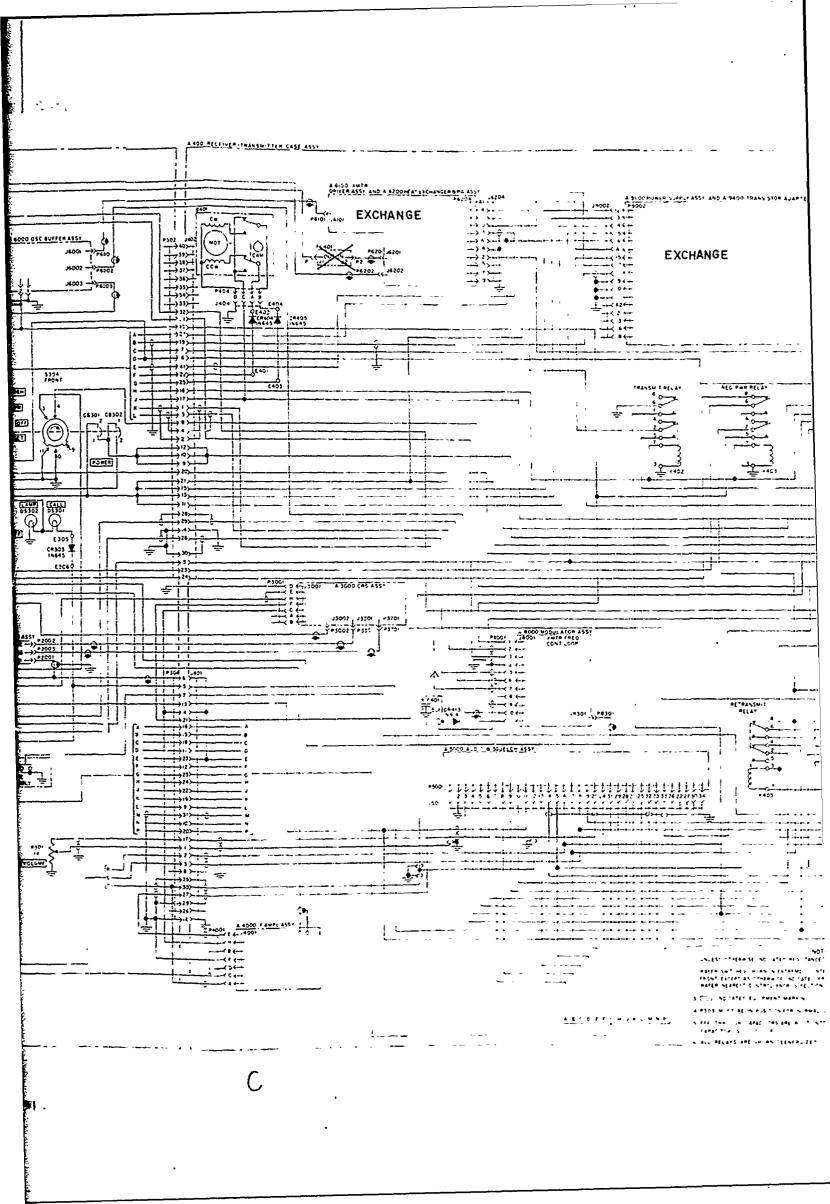
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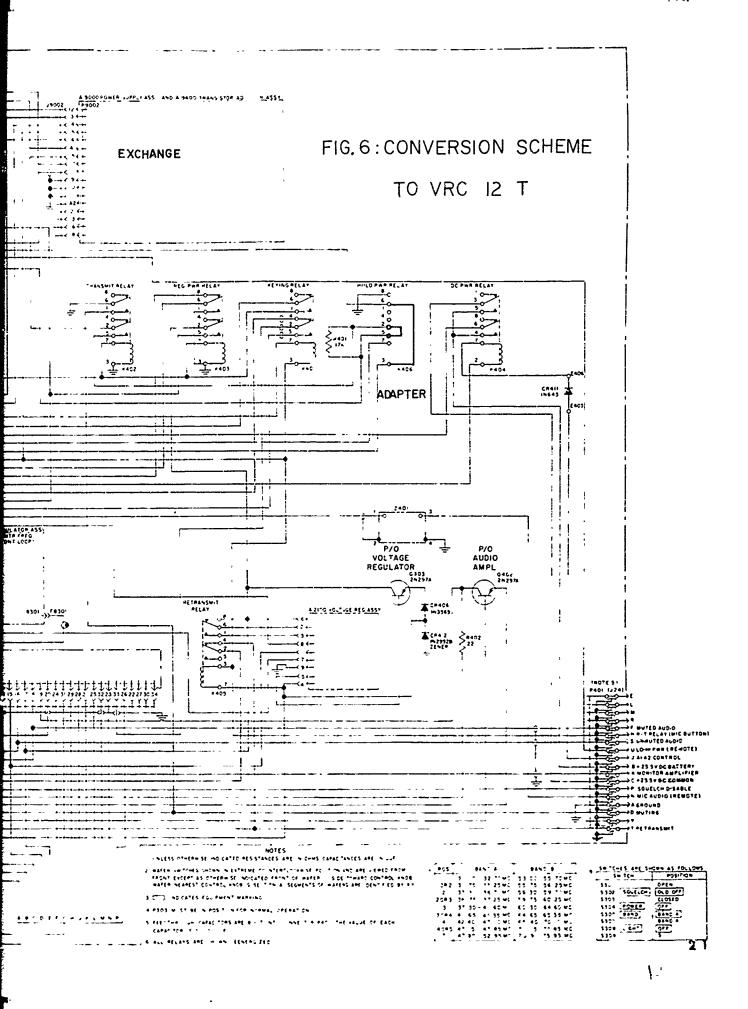
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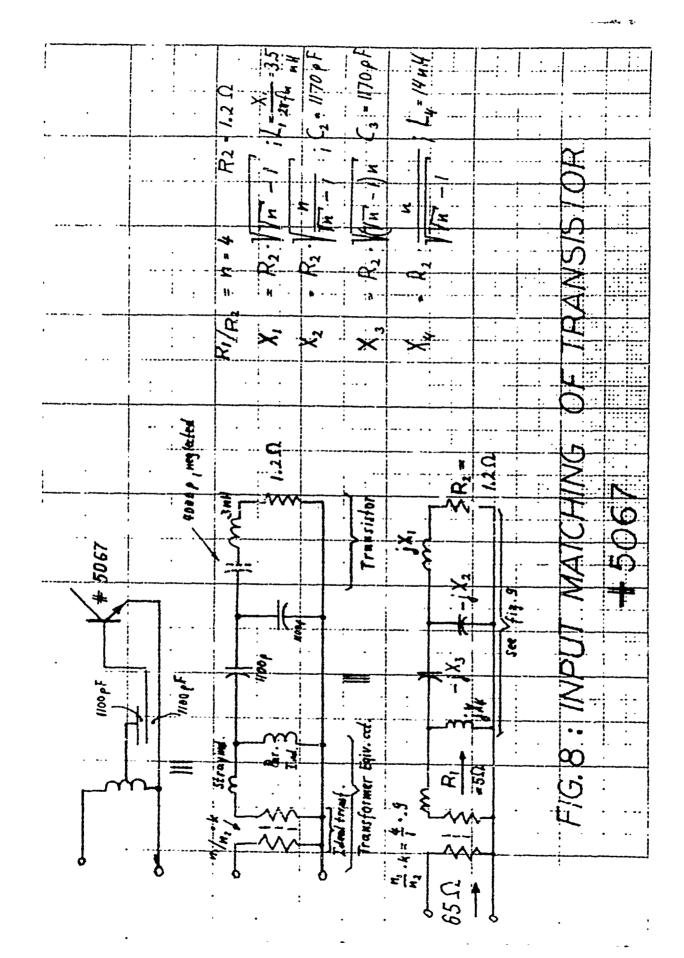


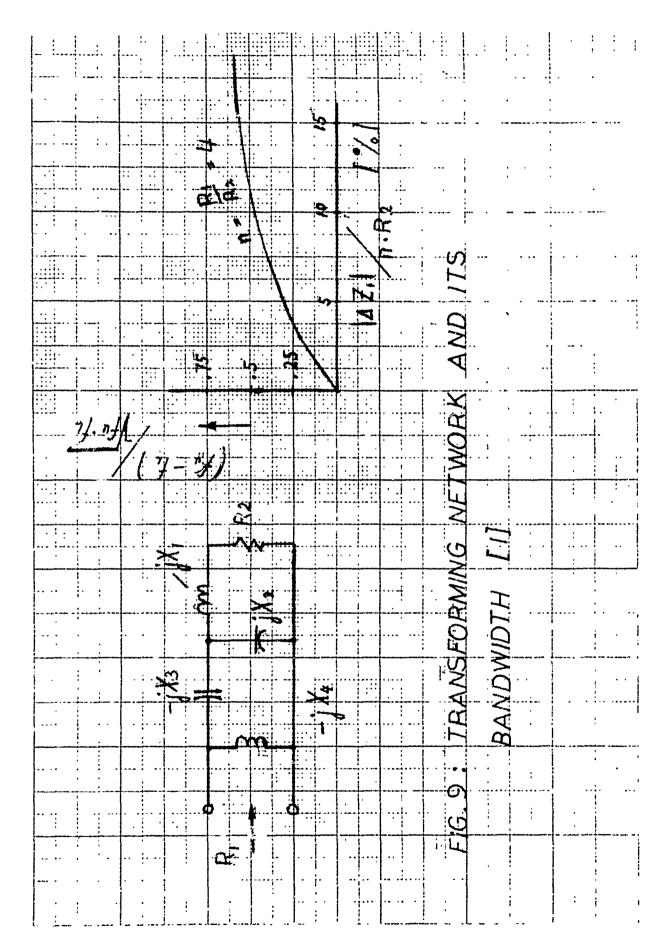


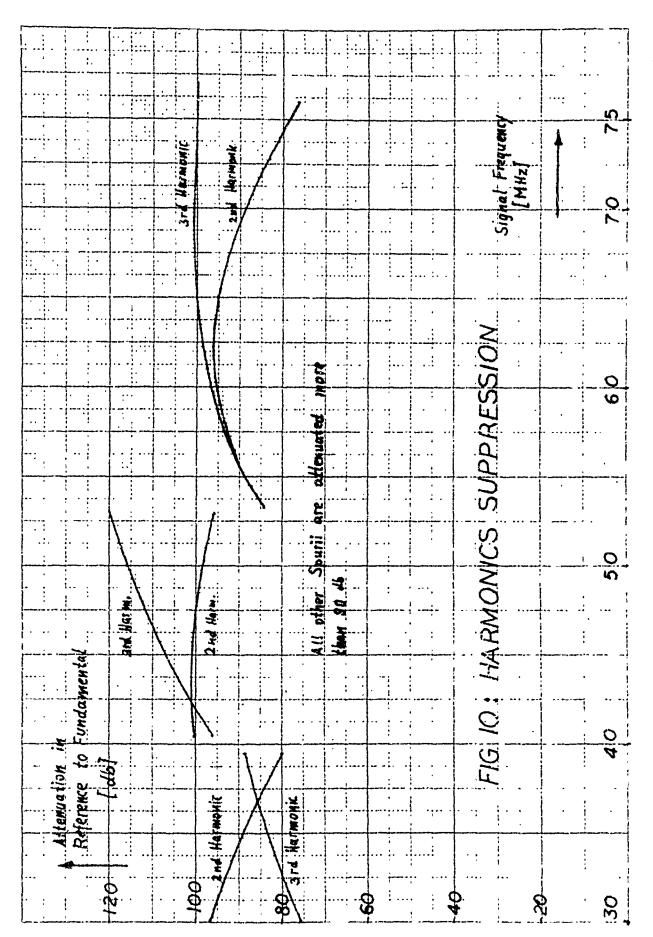
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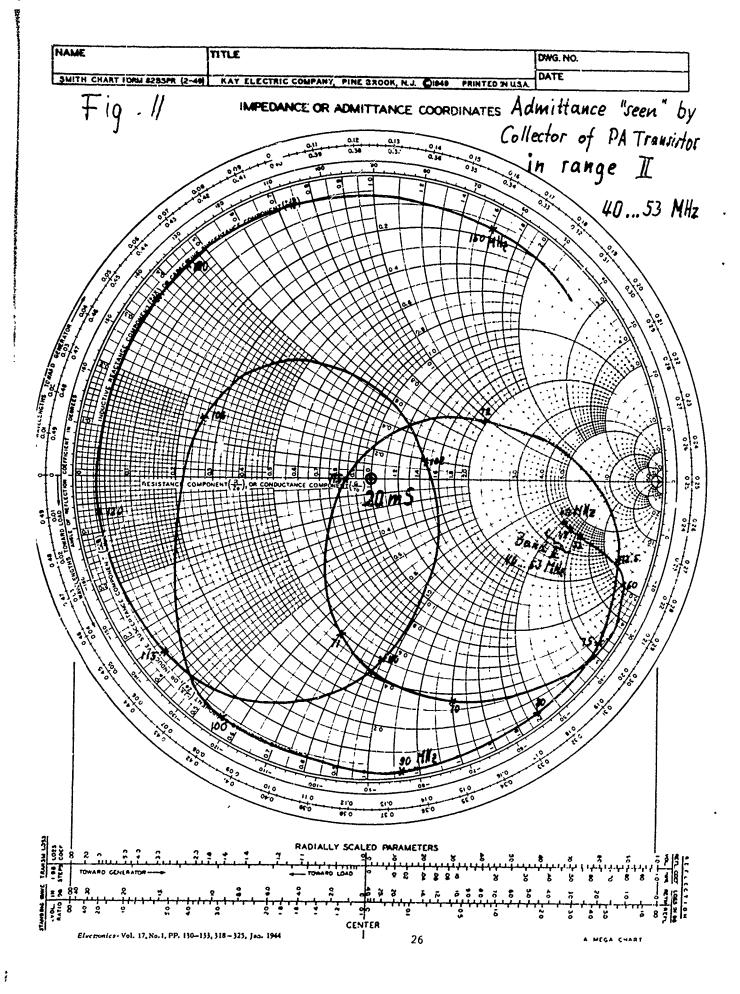


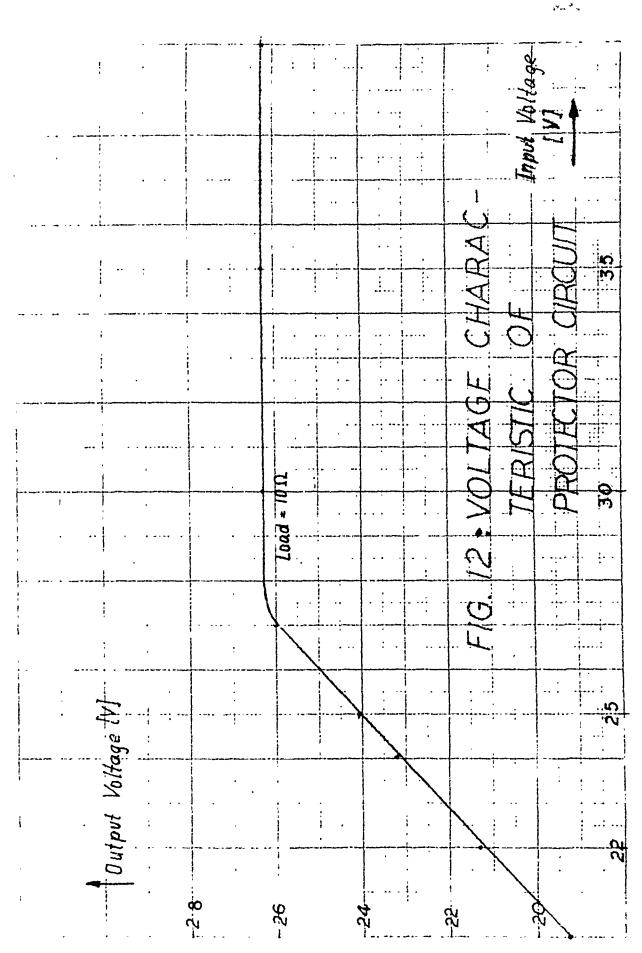
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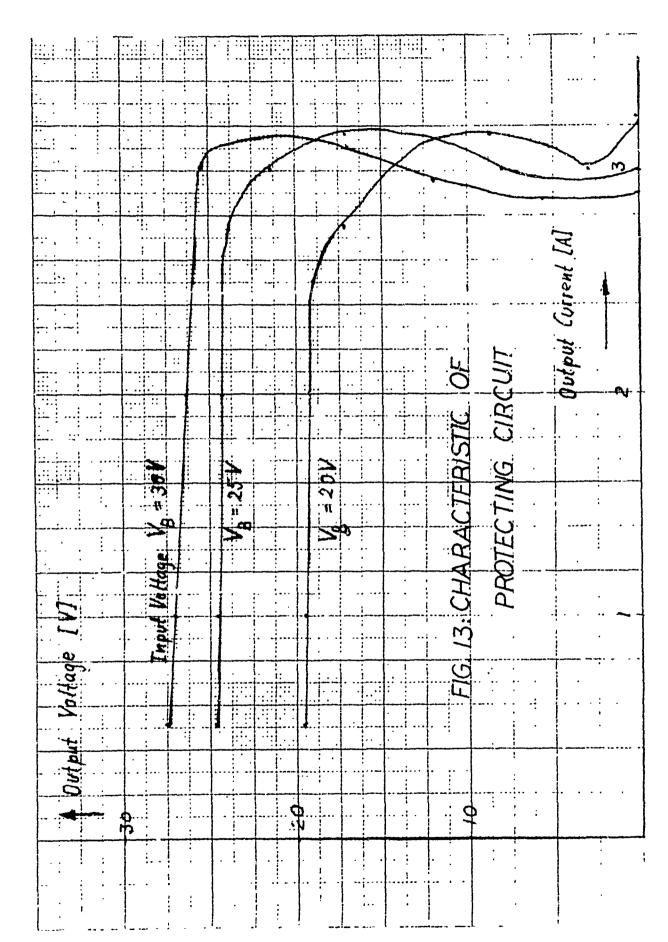






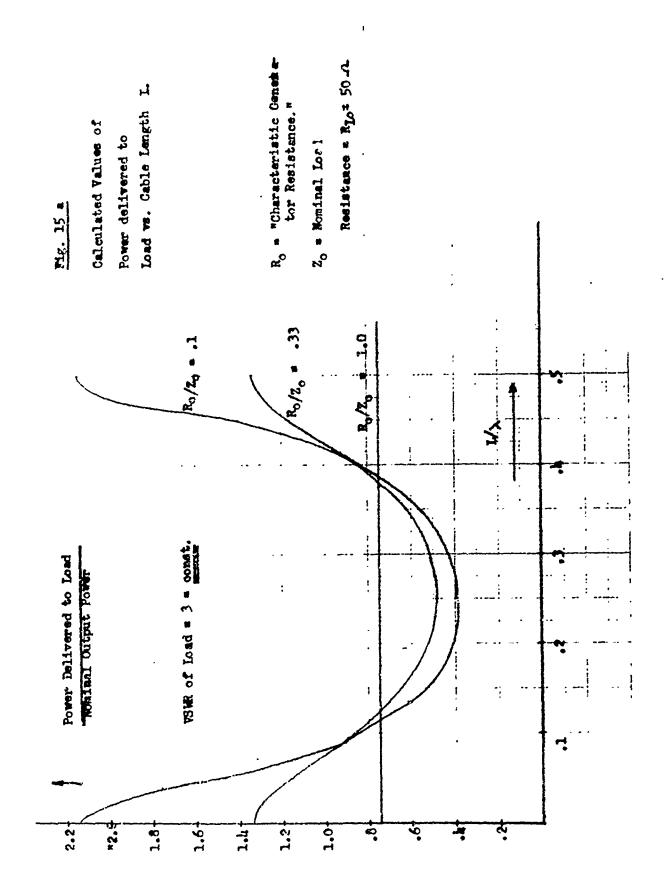






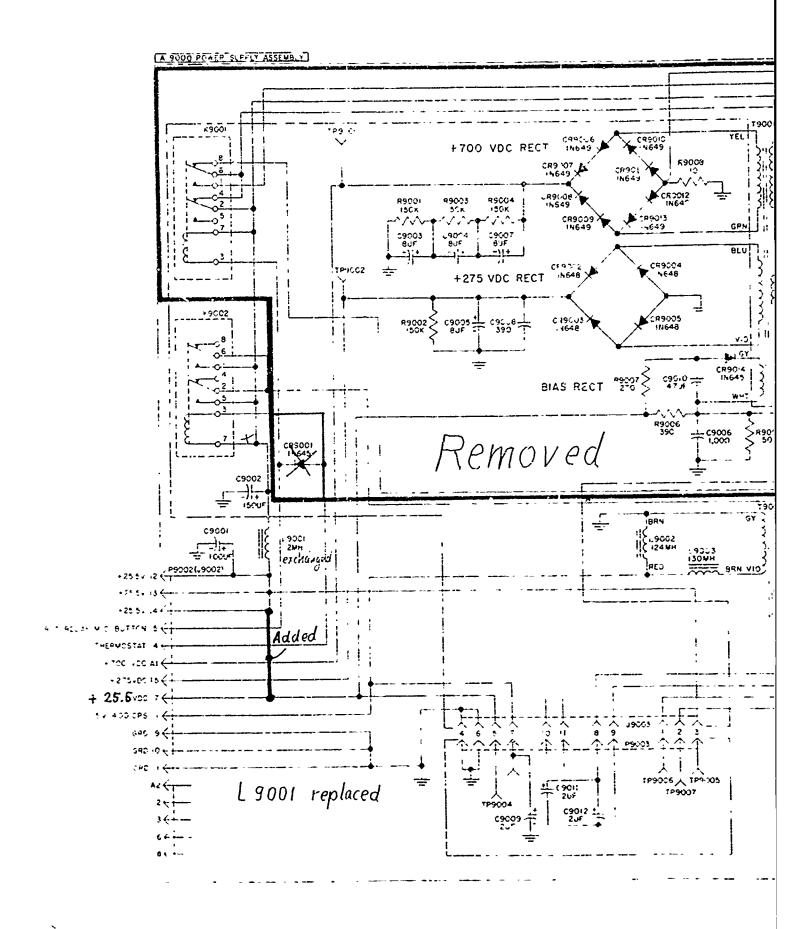
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A 94 2 TRANSIST Y ASARTEM 15 18 8.4 Remove POWER Fig. 17 Changes in Power Supply

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## 6. APPENDIX B

# Amplifier has 85% efficiency while providing

up to 10 watts power over a wide frequency band. A switching transistor is the key in the design.

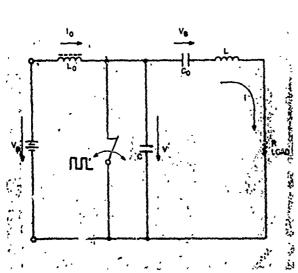
The efficiency of transistorized power amplifiers for cw operations can go as high as 85%, if the design is right. What's more, the amplifier can maintain its broadband characteristic.

The design approach centers on a transistor, used in a switching mode, that gives very high collector efficiencies.

To illustrate the advantages of this design, consider the outpu' power stages of conventional vhf communication equipment. The output powers are usually around 50 watts. If the efficiency of the cw power amplifiers is 60%, a bulky heat sink is needed to handle the dissipated power. If the efficiency is increased up to 80%, the dissipated power is halved.

A common requirement of communication systems, that the second harmonic be suppressed at the output, also helps achieve the high efficiency, since it lowers the bandwidth demands on the amplifier. The output circuit of the power am-

Dieter R. Lohrmann, Development Engineer, USAECOM, Ft. Monmouth, N. J.



1. Simplified equivalent circuit of transistor's collector circuit. The ideal switch represents the transistor. It is operated by the signal fed to its base-emittal circuit by the dc current  $I_o$ . When the voltage across C crosses zero, the switch will be closed. The collector-emitter capacitance,  $C_o$  is assumed to be independent of voltage,  $C_o$ , the dc blockling capacitor, charges to the battery voltage,  $V_B$ . The switch opens without any current.

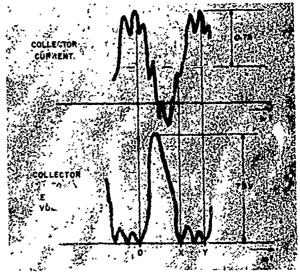
plifier has to cover a frequency range of less than 1:2 for each position of the range-selecting switch. This assumption is valid because the low-pass or bandpass filters used to suppress the second harmonic cover a frequency range of 1:1.8 to 1:1.5.

The criterion for achieving high collector efficiency is this: The impedance, seen from the base and looking into the matched circuit, should not be a short-circuit for the second harmonic over the whole frequency band.

The simplified equivalent circuit of the collector shows the transistor as a switch, being opened and closed periodically (Fig. 1). The choke  $L_{\mathfrak{d}}$  feeds a current to the collector of the transistor. The collector-emitter capacity is C, which, for simplicity, is assumed to be independent of voltage.

The dc blocking capacitor,  $C_o$ , charges to the bettery voltage. For simplicity, an inductor L, in series with the load resistor R, has been substituted for a low-pass filter.

To understand the operation of the circuit, let us assume that the switch has just been closed. After a sufficient amount of dc current I<sub>o</sub> has



2. Traces of the collector voltage and collector current indicate the open and closed periods. During the interval OX, the switch is open; during XY, it is closed. The collector current does not go to zero during the OFF period, because the collector capacitance is parallel to the switch. The transistor in the experiments is a type 2N3632, operated at 69 MHz.  $I_{\rm C}=0.45$  A,  $V_{\rm B}=25$  V. The output RF power is 9 watts with an input of 1 wait.

built up in  $L_n$  the switch is opened. If the circuit of C, L and R is underdamped, the voltage across C will be a damped oscillation.

After the first half cycle, when the voltage crosses zero again, the switch is closed. This collector voltage, r, is traced in Fig. 2. During the interval OX the switch is open; during XY it is closed. The collector current, recorded in proper phase, is not zero during the switch-off cycle, because the collector's capacity is parallel to the switch. (Fig. 2)

It seems reasonable to assume that one of the reasons why this circuit yields high collector efficiencies is this one:

At the end of the OFF cycle the collector-emitter voltage returns to zero by itself, due to the transient. Hence the voltage will go down to zero, switching in the transistor, without need for any current. Thus only a little power will be dissipated in the switching slopes.

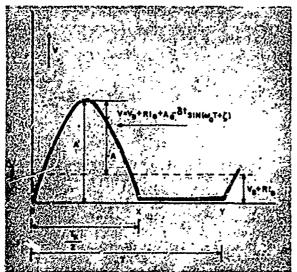
#### Linear equations described actions

Switching actions are usually described by a set of nonlinear differential equations. However, we can linearize them by using one set of linear equations for the ON interval and another for the OFF state.

The boundary conditions ar, provided by voltages and currents that must be at the end of the preceding interval to those at the beginning of the next one. The equations for the open position (Fig. 3) are:

$$C \frac{dv}{dt} + i = I_o, \tag{1}$$

$$v = V_B + Ri + L \frac{di}{dt}, 0 \le t \le \frac{T_L}{2}, \quad (2)$$



3. The basic switching action results in a simplified mathematical model. One set of linear equations describes the OFF condition, another is used for the ON state. Voltages and currents are used as boundary conditions, to match the two intervals. The time between zero crossings of the collector voltage curing the OFF period,  $T_{\rm k}$ , is about equal to the period time of the transient in the collector voltage.

and for the switch closed:

$$v=0, (3)$$

$$V_B + L \frac{di}{dt} + Ri = 0, \frac{T_A}{2} \le t \le T.$$
 (4)

These differential equations have very simple and well-known solutions. However, the equations for solving the boundary conditions become unwielding and nonlinear. Therefore we may use an approximate solution. The exact solution during the interval *OA* would be:

$$v = V_B + RI_o + Ae^{-\delta t} \sin (\omega_o t + \phi). \tag{5}$$

For this, the approximate form is:

$$v \approx A' \sin \omega_k t, \quad 0 \le t \le \frac{T_k}{2}$$
 (6)

with  $\omega_{k} = 2\pi/T_{k}$ . Using Fourier analysis, we can show that the peak value of the fundamental voltage in the waveform is:

$$v = \frac{A'}{1+k} \cdot \operatorname{Sa}\left[\frac{\pi}{2}\left(1-\frac{1}{k}\right)\right]. \tag{7}$$

Here  $k = T/T_{\lambda}$  and Sa  $x = \sin x/x$ .  $T_{\lambda}$  is the time between the points of zero crossings of the collector voltage during the OFF period. It is approximately equal to the period time of a transient in the collector voltage—that is, in the case of Fig. 1 it is:

$$T_{k} = \frac{2}{\sqrt{\frac{1}{LC} - \frac{R^{2}}{4L^{2}}}}.$$
 (8)

The output power at fundamental frequency is:

$$P_{out} = \frac{v^2}{2} G_{\omega}, \qquad (9)$$

where  $G_{\omega}$  is the real part of parallel admittance that the load circuit exhibits to the collector at the fundamental frequency.

Thus, in the case of Fig. 1:

$$G_{\omega} = Re\left(\frac{1}{R + j\omega L}\right) = \frac{R}{R^2 + \omega^2 L^2}$$
 (10)

Now A' is still unkown, but it can be found from dc considerations. The choke in Fig. 1 cannot have a dc drop. Therefore the dc component of the waveform in Fig. 3 must be equal to the battery voltage,  $V_B$ . In other words:

$$V_B = \frac{1}{T} \int_0^T v \ dt = \frac{1}{T} \int_0^{T_{k/2}} A' \sin \omega_k t \ dt \cdot \tag{11}$$

This yields

$$A' = \pi V_B \left(\frac{T}{T_k}\right), \qquad (12)$$

which is the peak collector voltage. If we put everything together, we have:

$$P_{out} = \frac{\Phi^2}{2} \frac{V_{B^2} k^2}{(1+k)^2} G_{\omega} \operatorname{Si}^2 \left[ \frac{\pi}{2} \left( 1 - \frac{1}{k} \right) \right], \quad (13)$$

where:

 $P_{out} = RF$  output power.

 $V_B$  = battery voltage. T = 1/(signal frequency).  $T_k$  = twice the length of cutoff interval—that is, twice the time between the zero crossings of the collector voltage. It is about equal to the cycletime of a transient in the collector circuit. In our example:

$$T_{\lambda} \approx \frac{2\pi}{\sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}}.$$

 $k = T/T_k.$ 

 $G_{\omega}$  = the real part of the load circuit's admittance exhibited toward the collector at the fundamental frequency. The collector's capacity is part of the circuit.

A' = the peak voltage at the collector.

If we let  $T = T_k$ , we get:

$$P_{out} = \frac{\pi^2}{8} V_B^2 G_{\omega},$$
 (14)

ənd

$$A' = \pi V_B. \tag{15}$$

As can be seen from these formulas, A' tends to increase as the frequency decreases.

For all these calculations we assumed that the output circuit is less than critically damped. This means, in the case of Fig. 1, that:

$$\frac{1}{LC} >> \frac{R}{4L^2} \tag{16}$$

 $\frac{1}{LC}>>\frac{R}{4L^2}. \tag{16}$  This condition is linked to the bandwidth of the load circuit, as shown in Fig. 4. The graph of the output power,  $P_{out}$ , over  $V_B{}^2G_{\omega}$  vs (signal frequency)  $(T_k)$ , indicates a nonlinear dependence.

A filter (low pass) in the collector circuit slightly modifies the above equations. In principle, the same formulas apply.  $G_{\nu}$  can be computed from the filter parameters. If  $Z_{\tau}/R_{\nu} = 0.85$ , then the eigenvalue of v will be  $p_1 = (-0.168 + j0.895)$  $(2\pi f_{\varrho})$ , where  $f_{\varrho}$  is the limiting frequency of the filter section—that is, the frequency at which the characteristic impedance turns imaginary. Hence  $T_{\lambda} = 0.895 f_{\varphi}.$ 

#### Practice modifies theories

Special requirements in an FM communication system demanded a power amplifier having about 10 watts output with a 10-dB amplification figure. It had to cover the frequency range of from 48 to 70 MHz with collector efficiencies up to 85%.

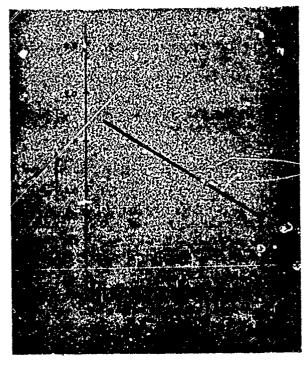
In the calculations thus far we neglected the following facts:

• The collector capacity of the transistor is dependent on voltage.

There is strong coupling between the input and output circuits via the base-to-collector capacity, which is nonlinear. As a matter of fact, part of the input power might go directly to the output over this path.

■ The switching will not happen instantaneously, and, most likely, not at exactly zero collector

• There are losses in the collector junction,



4. The normalized output power is a nonlinear function of the normalized frequency. The ordinate is  $V^2 \boldsymbol{G}_{\omega},$  and the abscissa is the signal frequency times T<sub>k</sub>.

which must be represented by a nonlinear resistor.

In the practical circuit we have a low-pass filter section in the collector circuit and not as simple a circuit as the one assumed in Fig. 1 for the calculation.

We got more accurate results by replacing  $V_B$ with  $V_B - V_{CE \, sat}$ , in Eqs. 13 and 14. The latter factor is the collector-emitter saturation voltage. This voltage is normally given by the manufacturer only for dc. For RF it seems to be on the order of 2 to 5 volts for a good transistor. So let us assume 3 volts, since a good guess is better than

The constant factor in Eq. 13 has been found to be 0.85, rather than  $\pi^2/8$ , in the practical circuit. Thus Eq. 14 becomes:

$$G_{\omega} = \frac{1}{R_{\omega}} = \frac{P_{out}}{0.85 (V_H - V_{rh,sat})^2}.$$

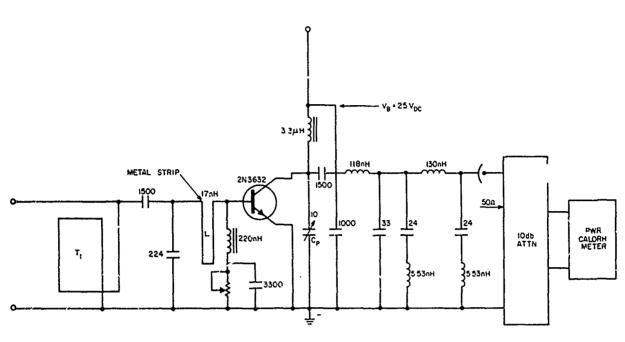
If  $P_{out}$  should be 10 watts at  $V_{H} = 25 \text{ V}$  battery voltage, then  $G_{\omega} = 24 \text{ mmho} \rightarrow 42 \text{ ohm is the}$ load admittance the collector will have to see at the signal frequency. Once this  $R_{\omega}$  is known, the first low-pass filter section can be designed. Forthe required amplifier, the frequency range desired was 50 to 75 MHz. Of course, the limiting frequency of the low-pass filter section must not be set to  $f_n = 75$  MHz, since the mismatch is much too large at the limiting frequency.

It works well if one arranges:

 $f_{\tau}$  = limiting frequency of low pass section  $1.5 f_n = 1.5 \times 75 \text{ MHz}.$ 

The chara 'ristic impedance of the low pass filter section is chosen as:

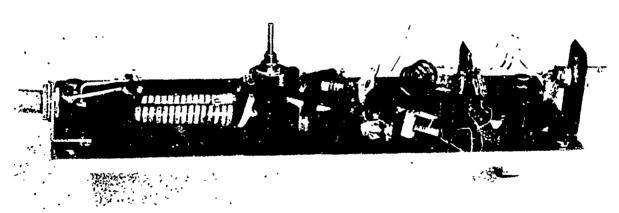
$$Z_{\tau} = 1.1 R_{\omega} \sim 1.1 \times 42 \Omega - 46 \Omega$$



NOTE: T<sub>1</sub> = 50-TO-12.5 OHM LINE TRANSFORMER CAPACITOR VALUES IN pF

5. Broadband power amplifier covers the frequency range from 48 to 70 MHz and has about 10 watts output power with 10-dB gain even if the dc path in the base circuit is

eliminated. (The calorimeter monitors the output power.) To lessen the danger of parametric oscillation, feeding chokes should have the lowest possible values.



6. Breadboard model of the circuit in Fig. 5 illustrates construction gimmicks. The inductance of 17 nH, in the input matching circuit, is made of a piece of metal strip

The input capacity of the section is known from filter theory:

$$C = \frac{1}{2\pi f_q Z_{\pi}} = 31 \text{ pF}.$$

On the collector side, one has to deduct the collector's capacity from the value.

Again from filter theory:

$$L=\frac{Z_{\pi}}{\pi f_g}=130 \text{ nH}.$$

The peak voltage between the collector and the emitter is expected to be in the inidiand.

folded like a hairpin. It can be adjusted very conveniently with a slug, suidered acros; the two legs. Mica capacitors satisfy the need for very low series lead inductances.

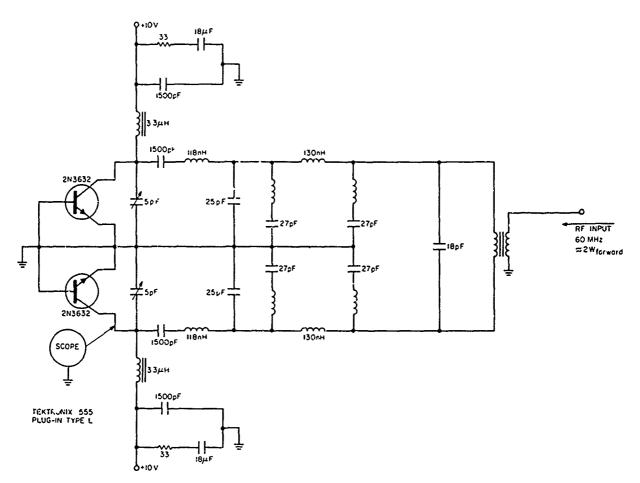
$$A' = \pi V_B = \pi 25 \text{ V} = 78 \text{ V},$$

which roughly agrees with measurements

The pi filter section is followed by another one, to give additional harmonic suppression. It has an attenuation pole at a frequency that is twice that of the midband value.

### Match input with transformers

To match the input, a broadband transmission line transformer  $T_1$  is used (Fig. 5). It transforms from 50 down to 12.5 plans, covering the entire range from 30 to 75 MHz. It is followed by



7. Broadband push-pull amplifier will brake out in parametric oscillations, even with its emitter and base leads grounded. (The oscilloscope picks up the parametric oscillations.) This proves the assumption that parametric os-

a matching section made up of a 224-pF capacitor and an inductor of 17 nH. The capacitor must have very low series lead inductance. Therefore a mica capacitor of the button type was used. The inductor was made of a piece of metal strip folded like a hairpin. It can be adjusted very conveniently by soldering a slug across it (Fig. 6).

Under operational conditions, the equivalent input circuit for the transistor has been found to be a series resistor of about 5 chms in the base lead, followed by a 1000-pF capacitor to ground.

Parallel to the 1000 pF capacitor is a resistor of about 10 ohms. About 200 pF of these 1000 are believed to be exhibited by the base-to-emitter junction. The remaining 800 pF is due to the Miller effect, caused by the collector's capacity. The circuit is valid between about 30 and 70 MHz.

The 224-pF capacitor, the 17-nH inductor and the equivalent input circuit of the transistor (5 ohms in series with about 1000 pF) form a broadband transformation network. It transforms the 5 ohms to 10 ohms and compensates for the 1000 pF.

The base is zero-biased. The biasing resistor is set to 10 ohms. At a 1-watt input driving power, the peak base-to-emitter reverse voltage is exceeded during the cutoff cycle, and reverse current is flowing. This reduces the dc current in the exter-

cillations are caused by a voltage-dependent capacitance in the collector and base circuit of the transistor, which gives rise to an undampening action. The capacitance acts like a varactor dir de in a parametric amplifier.

nal base circuit. As a matter of fact, the transistor still gives 10 watts of output power if the dc path in the base circuit is eliminated. According to the manufacturer, the transistor is not damaged, provided that less than 25% of the permissible dc power for the base junction is dissipated by back conduction. The back conduction effect seems to increase the steepness of the switching slopes, thus improving the collector's efficiency.

The resistance in the base circuit was chosen as 100 ohms, for dc stability.

A  $3.3-\mu H$  choke supplies the dc current to the collector. The collector circuit is formed by two low-pass pi filter sections that use the collector's capacity as part of the filter's input capacity. The trimmer in the collector line adjusts this output capacity. The second pi filter section has a pole at 141 MHz, to keep residual second harmonic power from being dissipated in the load.

A laboratory model, designed for 40 watts output power, is already being tested. The unit is similar to the one described below. It has the same high efficiency and a power gain of 10 dB.

#### Parametric oscillation is common problem

The tendency to break out in parametric oscilla-

tions seems to be a common problem to all highefficiency switched power-amplifier stages.

It is caused by the voltage-dependent capacitance in the collector and base circuits of the transistor. This capacitance is periodically varied by the signal itself. Therefore it acts like the varactor diode in a parametric amplifier (also called reactance amplifier). It is well known that such an amplifier may exhibit negative resistance under certain conditions, undampening the circuits. The circuit starts oscillating at some other frequency if this undamping action becomes too large. Therefore care must be taken to prevent the collector from sensing circuit resonances outside the passband, presumably at lower frequencies, down to dc. As a consequence, feeding chokes should have values as low as possible. On the power supply line, there must not be any resonant circuits at low frequencies. They can be eliminated by a resistor in series with a capacitor across the line.

The largest change of capacity of the collector junction occurs near zero collector voltage. Therefore linear stages, which do not use that portion of the characteristic, are much less likely to oscillate because of this effect; switched stages should be more troublesome.

A small collector capacity is more favorable than a large one for a given power output. Switching transistors with low losses—that is, with high efficiency—are more sensitive than those having higher losses. A small series resistor in the collector line helps, but it reduces the collector efficien-

To prove this hypothesis of parametric oscillations, we took a broadband push-pull amplifier and grounded all emitter and base leads with short, broad-ribbon leads (Fig. 7). Then we fed signal power into the output terminals of the amplifier. Fig. 8 shows the voltage waveforms at the collector. At a 0.4-watt input (the normal output power of the amplifier in normal operation is 25 watts) we still had a sine voltage at the collector (Fig. 8, top). But at 1.7-watts input, an oscillation of lower frequency suddenly appeared (Fig. 8, middle). At 2.7 watts the oscillation became noise-like (Fig. 8, bottom). Since these oscillations tend to kill the transistors, the experiment was made with a 10volt battery. The dc current in the transistors was zero until the oscillations started; then it jumped up to about 0.5 A, though the bases were grounded.

The differential equations describing these effects are basically of the Mathieu and Hill types, and the solutions have stable and unstable regio : •

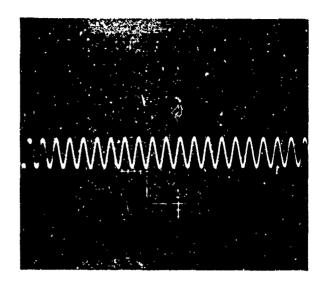
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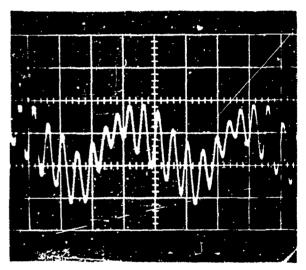
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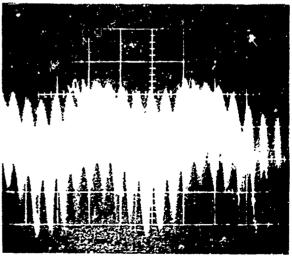
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8. Collector waveforms show effects of increased input and the result for receiving diation. At an input of 0.4 with 1.0 model, in the result of 0.4 with 1.0 model, and 0.4 model which becomes named to 0.27 with input (bottom). The docurrent jumped to 0.27 Model from zero as oscillations started, despite the grounded bases.

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